

Lorentzian α-Sasakian Manifold Satisfying Certain Pseudosymmetric Properties

Dr. Divyashree G. Department of Mathematics, Kuvempu University, Shankaraghatta - 577 451, Shimoga, Karnataka, INDIA. e-mail:gdivyashree9@gmail.com

Abstract: The purpose of the present paper is to study Lorentzian α -Sasakian manifold satisfying pseudo Ricci symmetric, Ricci generalized pseudo symmetric and generalized pseudo-Ricci symmetric conditions. Finally, we prove that Lorentzian α -Sasakian manifold satisfying the condition S \cdot R=0 reduces to Einstien manifold with scalar curvature – α^2 n(n-1).

Key words: Lorentzian α -Sasakian manifold, pseudo Ricci symmetric, Ricci generalized pseudo symmetric and generalized pseudo-Ricci symmetric, Ricci semisymmetric.

AMS Subject Classification: 53B30, 53C25, 53C50, 53D10.

1. Introduction:

Among the geometric properties of manifolds, symmetry is an important one and plays a significant role. Semisymmetric Riemannian manifolds was first studied by Cartan [1]. A Riemannian manifold M^n is called locally symmetric [12] if its curvature tensor R is parallel, i.e., $\nabla R = 0$. Α manifold M^n Riemannian is Riccisymmetric if its Ricci tensor S of type (0,2)satisfies $\nabla S = 0$, where ∇ denotes the Riemannian connection. ARiemannian manifold M^n is said to be semisymmetric if its curvature tensor R satisfies R(X, Y). R = $0, X, Y \in T(M^n)$, where R(X, Y) acts on R as a derivation [11,6].

Over the last five decades, the concept of Ricci-symmetric manifolds has been weakened by several authors to a different extent such as Ricci-recurrent manifolds [9], Ricci semisymmetric manifolds [11], pseudo Ricci-symmetric manifolds [4] Ricci pseudo symmetric manifold [4,5].

Lorentzian manifold plays a pivotal role in differential geometric point of view because of its wide significance properties. An *n*-dimensional smooth differentiable manifold *M* with Lorentzian metric *g* is known as Lorentzian manifold. The idea of Lorentzian manifolds was first introduced by Matsumoto [7] in 1989. The same idea was independently studied by Mihai and Rosca [8]. A differentiable manifold *M* of dimension *n* is said to be a Lorentzian α -Sasakian manifold if it admits a (1,1)-tensor field ϕ , a vector field ξ , a 1-form η and a Lorentzian metric *g* which satisfy the conditions

$\phi^2 = I + \eta \otimes \xi,$	(1.1)
$\eta(\xi) = -1, \ \phi\xi = 0, \ \eta(\phi X) = 0,$	(1.2)
$g(X,\xi)=\eta(X),$	(1.3)
$g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y),$	(1.4)
$(\nabla_X \phi)(Y) = \alpha[g(X, Y)\xi + \eta(Y)X],$	(1.5)

for all $X, Y \in T(M^n)$, where $T(M^n)$ is the Lie algebra of smooth vector fields on $T(M^n)$, α is smooth function on M^n and ∇ denotes the covariant differentiation operator of Lorentzian metric g [10,18].

On a Lorentzian α -Sasakian manifold [10,18], it can be shown that

$$\begin{aligned} \nabla_X \xi &= \alpha \phi X, \quad (1.6) \\ (\nabla_X \eta) Y &= \alpha g(\phi X, Y), \quad (1.7) \end{aligned}$$

An extensive studies on Lorentzian α -Sasakian manifolds are seen in the following papers [10,16,17,18] and others.

Motivated by the above studies, we plan to study pseudosymmetric conditions on Lorentzian α -Sasakian manifold.

Our paper is structured in the following way: Section 2 contains basics of Lorentzian α -Sasakian manifold. Section 3 deals with the study of pseudo Riccisymmetric Lorentzian α -Sasakian manifold. We proved that if an *n*-dimensional Lorentzian α -Sasakian manifold (n > 1) is generalized pseudo Ricci-symmetric then the sum of 1-forms is always non-zero, in section 4. In Section 5, we have shown that if an ndimensional Lorentzian α -Sasakian manifold (n > 1) satisfies Ricci generalized pseudosymmetric condition then it is an Einstein manifold, provided $nf \neq 1$. In the last section, we study Lorentzian α -Sasakian manifold satisfying the condition $S \cdot R=0$.

2. Lorentzian α-Sasakian manifolds

The authors [15,18] studied the characteristics of Lorentzian α -Sasakian manifold under different classes. The following relations hold on this manifold:

$\eta(R(X,Y)Z) = \alpha^2[g(Y,Z)\eta(X) -$	
$g(X,Z)\eta(Y)],$	(2.1)
$R(\xi, X)Y = \alpha^2[g(X, Y)\xi - \eta(Y)X],$	(2.2)
$R(X,Y)\xi = \alpha^2[\eta(Y)X - \eta(X)Y],$	(2.3)
$R(\xi, X)\xi = \alpha^2 [X + \eta(X)\xi],$	(2.4)
$S(X,\xi) = (n-1)\alpha^2 \eta(X),$	(2.5)
$S(\xi,\xi) = (n-1)\alpha^2,$	(2.6)
$S(\phi X, \phi Y) = S(X, Y) + (n - 1)$	
$1)\alpha^2\eta(X)\eta(Y),\qquad(2.7)$	

where R and S are the curvature tensor and the Ricci tensor respectively.

An *n*-dimensional Lorentzian α -Sasakian manifold is said to be Einstein manifold if it satisfies

$$S(Y,Z) = \alpha g(Y,Z), \quad (2.8)$$

where α is a constant.

3. On Pseudo Ricci-symmetric Lorentzian α -Sasakian manifold

In 1988, Chaki introduced the notion of pseudo Ricci-symmetric $(PRS)_n$ manifolds [4]. The same concept was studied by Tarafdar [13] on different manifold.

Definition: A non-flat Riemannian manifolds (M^n, g) is called pseudo Riccisymmetric if its Ricci tensor S is not identically zero and satisfies the following condition

$$(\nabla_X S)(Y,Z) = 2G(X)S(Y,Z) + G(Y)S(X,Z) + G(Z)S(Y,X),$$
(3.1)

where G is a non-zero 1-form and

$$g(X,P) = G(X). \tag{3.2}$$

Suppose that equations (3.1) and (3.2) are satisfied in an *n*-dimensional Lorentzian α -Sasakian manifold (n > 1). By taking cyclic sum of (3.1), one can get

$$(\nabla_X S)(Y,Z) + (\nabla_Y S)(Z,X) + (\nabla_Z S)(X,Y) = 4\{G(X)S(Y,Z) + G(Y)S(X,Z) + G(Z)S(Y,X)\}.$$
(3.3)

Now, admitting a cyclic Ricci tensor in (3.3), we have

$$G(X)S(Y,Z) + G(Y)S(X,Z) + G(Z)S(Y,X) = 0.$$
 (3.4)

Plugging *Z* by ξ in (3.4) and using (2.5), we obtain

$$(n-1)\alpha^2 G(X)\eta(Y) + (n-1)\alpha^2 G(Y)\eta(X) + G(\xi)S(X,Y) = 0. (3.5)$$

In a similar manner, treating $Y = \xi$ in the above equation and using (1.2) and (2.5), we get

$$(n-1)\alpha^2 G(X) + 2(n-1)\alpha^2 G(\xi)\eta(X) = 0,$$
(3.6)

which implies that

$$G(X) = 2G(\xi)\eta(X).$$
 (3.7)



Again, continuing the process by putting $X = \xi$ in (3.6) and using (1.2), finally we see that

$$\eta(P) = 0. \tag{3.8}$$

Hence we can state the following theorem:

Theorem: If a pseudo Ricci-symmetric Lorentzian α -Sasakian manifold (n > 1) admits a cyclic parallel Ricci tensor then the 1-form *G* must vanish.

4. On Generalized Pseudo Riccisymmetric Lorentzian α -Sasakian manifold

Definition: A non-flat Riemannian manifold (M^n, g) (n > 1) is called generalized pseudo Ricci-symmetric [2] if its Ricci tensor *S* of type (0,2) is not identically zero and satisfies the following condition

$$(\nabla_X S)(Y,Z) = 2A(X)S(Y,Z) + B(Y)S(X,Z) + C(Z)S(X,Y),$$
(4.1)

where A, B and C are three non-zero 1-forms.

Definition: Let M^n be a *n*-dimensional generalized pseudo Ricci-symmetric Lorentzian α -Sasakian manifold.

By substituting Z by ξ in (4.1) and using (2.5), we get

 $(\nabla_X S)(Y,\xi) = 2(n-1)\alpha^2 A(X)\eta(Y) + (n-1)\alpha^2 B(Y)\eta(X) + C(\xi)S(X,Y).$ (4.2)

Also we find,

$$(\nabla_X S)(Y,\xi) = (n-1)\alpha^3 g(\phi X,Y) - \alpha S(\phi X,Y).$$
(4.3)

On equating the RHS of (4.2) and (4.3), we obtain

$$\begin{aligned} &(n-1)\alpha^3 g(\phi X,Y) - \alpha S(\phi X,Y) = 2(n-1)\alpha^2 A(X)\eta(Y) \\ &+ (n-1)\alpha^2 B(Y)\eta(X) + C(\xi)S(X,Y). \end{aligned}$$

Now, treating $X = Y = \xi$ in (4.4) and using (1.2) and (2.6), we have

 $[2A(\xi) + B(\xi) + C(\xi)] = 0.$ (4.5)

Suppose $(n-1)\alpha^2 \neq 0$ then the 1-form 2A + B + C over the killing vector field ξ of (M^n, g) vanishes.

Further, replacing X by ξ in (4.2) and using (1.2), (2.5), (4.3) and (4.5), we get

$$B(Y) = -B(\xi)\eta(Y).$$
 (4.6)

Similarly, in (4.2) taking $Y = \xi$ and using (1.2), (2.5), (4.3) and (4.5), we have

$$2A(X) = -2A(\xi)\eta(X).$$
 (4.7)

Likewise, substituting $X = Y = \xi$ in (4.1) and using (2.5), (4.3) and (4.5), we see that

$$C(Z) = -C(\xi)\eta(Z). \tag{4.8}$$

In view of (4.6), (4.7) and (4.8), finally we obtain

$$[2A(X) + B(X) + C(X)] = 0.$$
(4.9)

Hence, we state the following theorem: Theorem: If an *n*-dimensional Lorentzian α -Sasakian manifold (n > 1) is generalized pseudo Ricci-symmetric then the sum of 1forms is always non-zero.

5. On Ricci Generalized Pseudosymmetric Lorentzian α -Sasakian manifold

Definition: A Riemannian manifold (M^n, g) (n > 1) is said to be Ricci generalized pseudosymmetric [14,16] if and only if the relation

$$R \cdot R = fQ(S, R), \tag{5.1}$$

holds on the set $U = \{x \in M^n : Q(S, R) \neq 0\}$ at *x*, where *f* is a some function on *U*. Also, we define endomorphisms R(X, Y) and $X \wedge_4 Y$ by

$$R(\vec{X}, Y)\vec{Z} = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z,$$
(5.2)

and

$$(X \wedge_A Y)Z = A(Y,Z)X - A(X,Z)Y, (5.3)$$

respectively, where $X, Y, Z \in T(M^n)$, $T(M^n)$ is the set of all differentiable vector fields on M^n , A is the symmetric (0,2)-tensor.

JNNCE Journal of Engineering & Management (JJEM)

Let us consider that an *n*-dimensional Ricci generalized pseudosymmetric Lorentzian α -Sasakian manifold (n > 1).

In view of (5.1), we can have

 $(R(X,Y) \cdot R)(U,V)W = f((X \wedge_S Y) \cdot R)(U,V)W,$ (5.4)

which follows that

 $\begin{aligned} R(X,Y)R(U,V)W &- R(R(X,Y)U,V)W - \\ R(U,R(X,Y)V)W &- R(U,V)R(X,Y)W = \\ f[(X \wedge_S Y)R(U,V)W - R((X \wedge_S Y)U,V - \\ R(U,(X \wedge_S Y)V)W - R(U,V)(X \wedge_S Y)W]. \\ (5.5) \end{aligned}$

From the equations (5.3) and (5.5), we get R(X,Y)R(U,V)W - R(R(X,Y)U,V)W - R(U,R(X,Y)V)W - R(U,V)R(X,Y)W = f[S(Y,R(U,V)W)X - S(X,R(U,V)W)Y - S(Y,U)R(X,V)W + S(X,U)R(Y,V)W - S(Y,V)R(U,X) + S(X,V)R(U,Y)W - S(Y,W)R(U,V)X + S(X,W)R(U,V)Y].(5.6)

Replacing X and U by ξ in the above equation and after simplification, one can obtain

$$\begin{aligned} &\alpha^{4}ag(V,W)Y - \alpha^{2}R(Y,V)W - \\ &\alpha^{4}g(Y,W)V = f[-\alpha^{2}S(Y,V)\eta(W)\xi + \\ &\alpha^{4}g(V,W)Y - (n-1)\alpha^{2}R(Y,V)W + \\ &(n-1)\alpha^{4}g(Y,W)\eta(V)\xi - \alpha^{2}S(Y,W)V + (n-1)\alpha^{4}g(V,Y)\eta(W)\xi]. \quad (5.7) \end{aligned}$$
Now, taking inner product with *T* in (5.7) and using (1.3), we get
$$\begin{aligned} &\alpha^{4}g(V,W)g(Y,T) - \alpha^{2}g(R(Y,V)W,T) - \\ &\alpha^{4}g(Y,W)g(V,T = \\ &f[-\alpha^{2}S(Y,V)\eta(W)\eta(T) + (n-1)\alpha^{4}g(V,W)g(Y,T) - (n-1)\alpha^{2}g(R(Y,V)W,T) + (n-1)\alpha^{4}g(Y,W)\eta(V)\eta(T) - \\ &\alpha^{2}S(Y,W)\eta(V)\eta(T) - \\ &\alpha^{2}S(Y,W)\eta(V)\eta(T) - \\ &\alpha^{2}S(Y,W)g(V,T) + (n-1)\alpha^{4}g(V,Y)\eta(W)\eta(T)]. \end{aligned}$$

Contracting the above equation, we obtain $[S(Y,T) - (n-1)\alpha^2 g(Y,T)] = nf[S(Y,T) - (n-1)\alpha^2 g(Y,T)],$ (5.9) which implies

 $(1 - nf)[S(Y,T) - \alpha^2(n-1)g(Y,T)] = 0.$ (5.10)

Then either $f = \frac{1}{n}$ or the manifold is an Einstein manifold of the following form $S(Y,T) = (n-1) \alpha^2 g(Y,T)$. (5.11) Therefore, the above equation yields $r = n(n-1) \alpha^2$, (5.12) Where *r* is a scalar curvature.

Thus, the theorem can be stated as follows: Theorem: Let (M^n) be an *n*-dimensional Lorentzian α -Sasakian manifold (n > 1). If such a manifold satisfies Ricci generalized pseudosymmetric condition then the manifold is an Einstein manifold, provided $nf \neq 1$ with scalar curvature as in (5.12).

6. Lorentzian α -Sasakian manifold satisfying the condition $S \cdot R = 0$.

Consider an *n*-dimensional Lorentzian α -Sasakian manifold (n > 1) satisfying the curvature condition $S \cdot R = 0$. Then, we have $(S(X,Y) \cdot R)(U,V)W = 0$, (6.1) which implies $(X \wedge_S Y)R(U,V)W +$ $R((X \wedge_S Y)U,V)W + R(U,(X \wedge_Y)V) +$ $R(U,V)(X \wedge_S Y)W = 0$. (6.2) Making use of (5.3) in (6.2), we get

$$(Y, R(U, V)W)X - S(X, R(U, V)W)Y + S(Y, U)R(X, V)W - S(X, U)R(Y, V)W + S(Y, V)R(U, X)W - S(X, V)R(U, Y)W + S(Y, W)R(U, V)X$$

-S(X,W)R(U,V)Y = 0. (6.3)

S

Substituting $U = W = \xi$ in (6.3) and using (2.3), (2.4) and (2.5), we find that

 $\alpha^{2}S(Y,V)X - \alpha^{2}S(X,V)Y + \alpha^{2}S(Y,V)X - \alpha^{2}S(X,V) + 2(n - 1)\alpha^{4}\eta(V)\eta(Y)X - 2(n - 1)\alpha^{4}\eta(V)\eta(X)Y - 2(n - 1)\alpha^{4}\eta(X)\eta(Y) + \alpha^{2}S(Y,V)\eta(X)\xi - \alpha^{2}S(X,V)\eta(Y)\xi + -(n - 1)\alpha^{4}g(V,Y)\eta(X)\xi.$ (6.4) By taking innerproduct of the above equation with ξ and replacing X by ξ , we obtain

$$\alpha^{2}[S(U,W) + (n-1)\alpha^{2}g(U,W)] = 0,$$
(6.5)

Which means either $\alpha^2 = 0$ (contradiction) or the manifold becomes Einstein manifold. So, we have

 $S(U,W) = -(n-1)\alpha^2 g(U,W),$ (6.6) Which in turn yields

 $r = -n(n-1)\alpha^2$. (6.7)

This leads to the following statement:

Theorem: If an *n*-dimensional Lorentzian α -Sasakian manifold (n > 1) satisfies the curvature condition $S \cdot R = 0$, then the manifold is an Einstein manifold with negative scalar curvature as in (6.7).

Acknowledgement: The author is thankful to UGC in the form of Rajiv Gandhi National Fellowship (F1-17.1/2015-16/RGNF-2015-17-SC-KAR-26367).

Bibliography

- [1] Cartan E, "Sur une classe remarquable despaces de Riemannian", Bull. Soc. Math. France, 54, 214-264, 1926.
- [2] M. C. Chaki and S. Koley, "On generalized pseudo Ricci symmetric manifolds", Periodica Mathematica Hungarica, 28(2), 123-129, 1993.
- [3] M.C. Chaki, "On pseudo-symmetric manifolds", An. Sti. Ale Univ., AL. I. CUZA" Din Iasi, 33, 53-58, 1987.
- [4] M.C. Chaki, "On pseudo Ricci symmetric manifolds", Bulg. J. Phys., 15, 526-531, 1988.
- [5] R. Deszcz, "On Riccipseudosymmetric warped products", Demonstratio Math., 22, 1053-1065, 1989.
- [6] O. Kowalski, "An explicit classification of 3-dimensional Riemannian spaces satisfying $R(X, Y) \cdot R = 0$ ", Czechoslovak Math. J. 46(121), 3, 427-474, 1996.
- [7] Matsumoto K, "On Lorentzian para contact manifolds", Bull.Yamagata Univ.Nat. Sci. 12, 151-156, 1989.
- [8] Mihai I. and Rosca, "On Lorentzian manifolds", Classical analysis world scientific Pable, 1992.

- [9] E.M. Patterson, "Some theorems on Ricci-recurrent spaces", J. London Math. Soc., 27, 287-295, 1952.
- [10] Prakasha D.G, Bagewadi C.S. and Basavarajappa N.S, "On pseudosymmetric Lorentzian α -Sasakian manifolds", Int. J. Pure Appl. Math. 48, 57-65, 2008.
- [11] Z.I. Szabo, "Structure theorems on Riemannian space satisfying $R(X, Y) \cdot R = 0$ ", I, The local version, J. Differential Geom., 17, 531, 1982.
- [12] Takahashi T, "Sasakian ϕ -symmetric spaces", Tohoku Math. J. 29, 91-113, 1977.
- [13] Tarafdar M, "On pseudo-symmetric and pseudo-Ricci-symmetric Sasakian manifolds", Period. Math. Hungar. 22, 125-128, 1991.
- [14] L. Verstraelen, "Comments on pseudo-symmetry in sense of *R*. Deszcz, in: Geometry and Topology of submanifolds", World Sci. Publishing, 6, 199-209, 1994.
- [15] Yildiz A. and Murathan C, "On Lorentzian α-Sasakian manifolds", Kyungpook Math. J. 45, 95-103, 2005.
- [16] Yildiz A. and Murathan C, "Ricci generalized pseudo-parallel Kaehlerian submanifolds in complex space forms", Bull Malays Math Sci Soc (2), 31(2), 153-163, 2008.
- [17] Yildiz A. and Turan M, "A class of Lorentzian α-Sasakian manifolds", Kyungpook Math. J. 49, 789-799, 2009.
- [18] Yildiz, A, Turan M. and Acet B.E, "On three-dimensional Lorentzian α -Sasakian manifolds", Bull. Math. Anal. Appl. 1, 90-98, 2009.